

A Bayesian model for joint unmixing, clustering and classification of hyperspectral data

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Context

Hyperspectral imaging

Objective

Model

Spectral unmixing

Clustering

Classification

Experiments

Synthetic data

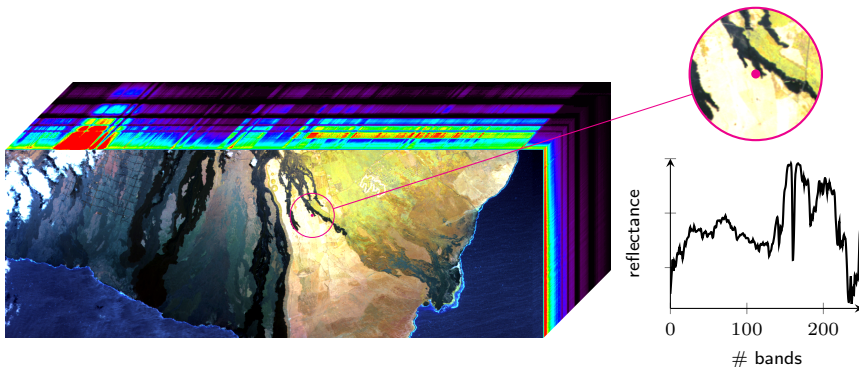
Real data

Conclusions and perspectives

Nature of an hyperspectral image

A remote sensing hyperspectral image is:

- same area at different wavelength → **hundreds of measurements** per pixel,
- poor spatial resolution due to sensor limitations, e.g., resolution around 10x10m per pixel for aerial applications

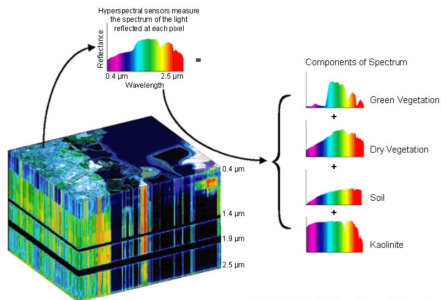


Hyperspectral image analysis

SPECTRAL UNMIXING

$$\mathbf{y}_p \approx \mathbf{M} \mathbf{a}_p$$

- \mathbf{y}_p : p-th observation
- \mathbf{M} : endmember matrix (spectra of elementary components)
- \mathbf{a}_p : p-th abundance vector



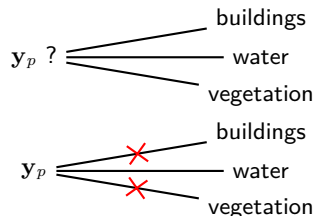
(NEMO Project Office, United States Navy)

CLASSIFICATION

Maximum a posteriori (MAP) rule:

$$\mathbf{y}_p \text{ belongs to } j \Leftrightarrow j = \arg \max_{j \in \mathcal{J}} p(j|\mathbf{y}_p),$$

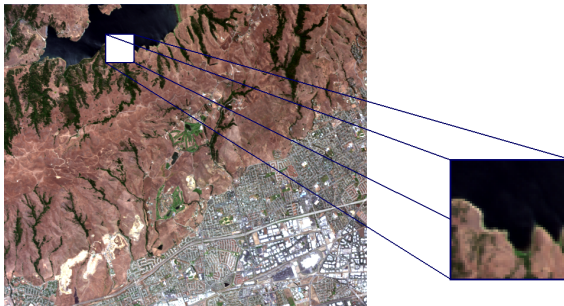
$$\Leftrightarrow j = \arg \max_{j \in \mathcal{J}} p(j)p(\mathbf{y}_p|j).$$



Spectral unmixing

One illustrative example

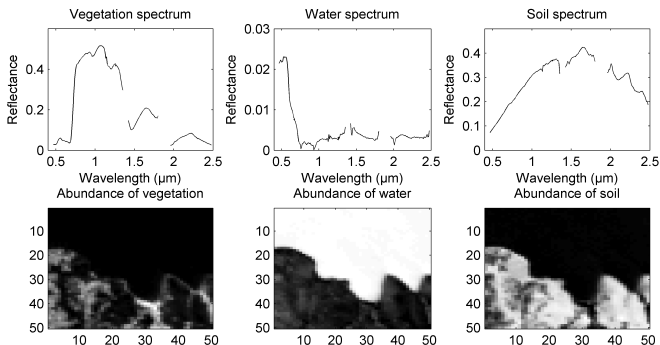
- Image: 50×50 pixels (Moffett field), $L = 224$ bands,
- 3 materials: vegetation, water, soil.



Spectral unmixing

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Spectral unmixing

A *matrix factorization, latent factor modeling or blind source separation* problem: $\mathbf{Y} \approx \mathbf{M}\mathbf{A}$

1. Principal Component Analysis (PCA)

- ▶ Searching for **orthogonal** “principal components” (PCs) \mathbf{m}_r ,
- ▶ PCs = directions with maximal variance in the data,
- ▶ Generally used as a dimension reduction procedure.

2. Independent Component Analysis (ICA) (of \mathbf{Y}^T)

- ▶ Maximizing the statistical **independence** between the sources \mathbf{m}_r ,
- ▶ Several measures of independence \Rightarrow several algorithms.

3. Nonnegative Matrix Factorization (NMF)

- ▶ Searching for \mathbf{M} et \mathbf{A} with **positive** entries,
- ▶ Several measures of divergence $d(\cdot|\cdot) \Rightarrow$ several algorithms.

4. (Fully Constrained) Spectral Mixture Analysis (SMA)

- ▶ **Positivity** constraints on $\mathbf{m}_r \Rightarrow$ positive “sources”
- ▶ **Positivity** and **sum-to-one** constraints on \mathbf{a}_r
 \Rightarrow mixing coefficients = proportions/concentrations/probabilities.

Objective

Spectral unmixing	Classification
Low-level biophysical information	High-level semantic information
Abundance vector per pixel	Unique label per pixel
Unsupervised	Supervised

⇒ **Scarcely considered jointly.**

Objective

Propose a **unified framework** to estimate jointly a classification map and a spectral unmixing from an hyperspectral image.

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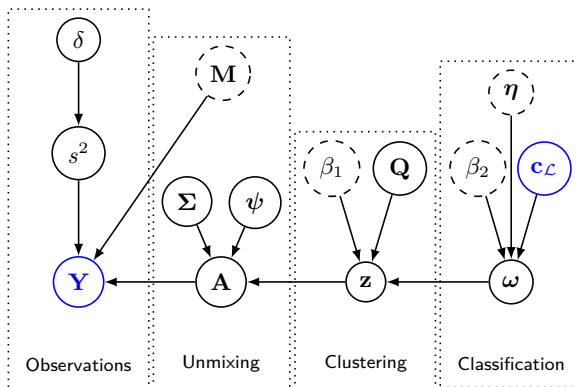
Synthetic data

Real data

Conclusions and perspectives

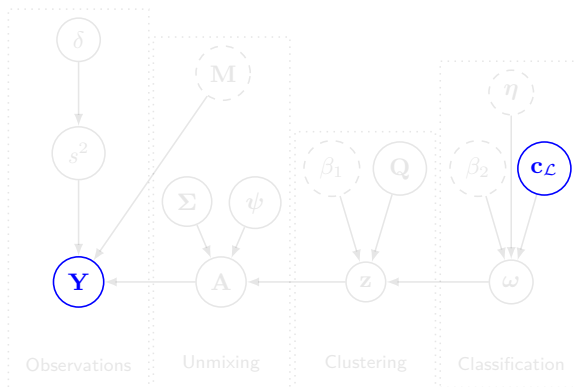
Bayesian model

- conventional linear mixing model;
- clustering of homogeneous abundance vectors;
- classification with a non-homogeneous Markov random field (MRF) to promote coherence between cluster and class labels.



Bayesian model

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Linear Mixture Model (1)

Linear combination of elementary signatures corrupted by an additive Gaussian noise

$$\mathbf{y}_p = \mathbf{M}\mathbf{a}_p + \mathbf{n}_p$$

with

- \mathbf{y}_p : measured spectrum ($p = 1, \dots, P$ where P is the total number of pixels)
- \mathbf{M} : endmember matrix
(i.e., spectra of R elementary components, assumed to be known here)
- \mathbf{a}_p : abundance vector
- \mathbf{n}_p : noise

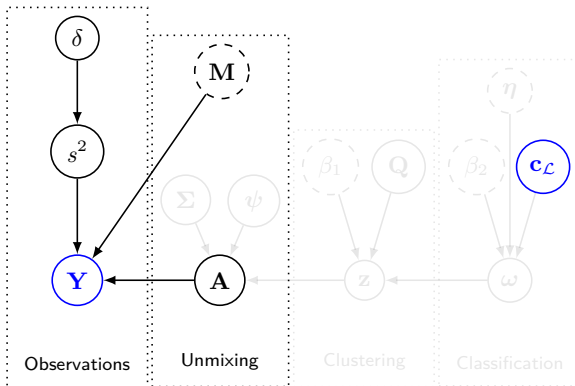
Linear Mixture Model (2)

Prior model for the noise:

$$\mathbf{n}_p | s^2 \sim \mathcal{N}(\mathbf{0}_D, s^2 \mathbf{I}_D),$$

$$s^2 | \delta \sim \mathcal{IG}(1, \delta), \quad p(\delta | s^2) \propto \frac{1}{\delta} \mathbb{1}_{\mathbb{R}^+}(\delta).$$

Hierarchical model



Clustering (1)

- Assumption: several unknown **spectrally coherent clusters** with statistically homogeneous abundance vectors, $\forall k \in \{1, \dots, K\}$,

$$\mathbf{a}_p | z_p = k, \boldsymbol{\psi}_k, \boldsymbol{\Sigma}_k \sim \mathcal{N}(\boldsymbol{\psi}_k, \boldsymbol{\Sigma}_k) \text{ with } \boldsymbol{\Sigma}_k = \text{diag}(\sigma_{k,1}, \dots, \sigma_{k,R})$$

where z_1, \dots, z_p are discrete labels identifying the belonging to the clusters.

- Vague priors for cluster parameters:

- ▶ $\boldsymbol{\psi}_k \sim \text{Dir}(\mathbf{1})$
→ ensures nonnegativity and sum-to-one constraints of $\mathbb{E}[\mathbf{a}_p | z_p = k]$
(*soft constraints on \mathbf{a}_p*)
- ▶ $\sigma_{k,r} \sim \mathcal{IG}(1, 0.1)$

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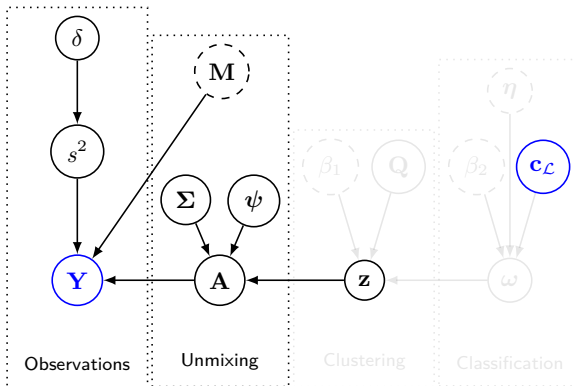
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Hierarchical model



Clustering (2)

Clustering with a **non-homogeneous Markov random field**

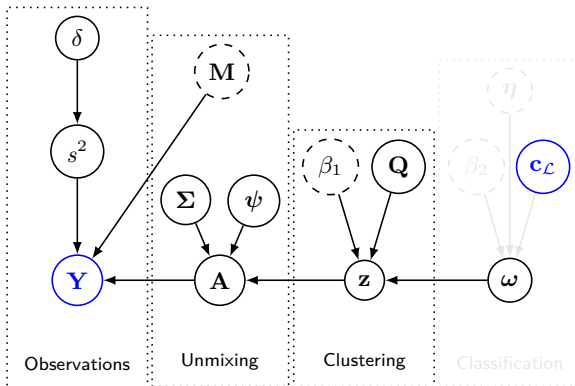
$$P[z_p = k | \mathbf{z}_{\mathcal{V}(p)}, \omega_p, q_{k, \omega_p}] \propto \exp \left(V_1(k, \omega_p, q_{k, \omega_p}) + \sum_{p' \in \mathcal{V}(p)} V_2(k, z_{p'}) \right)$$

with $\mathcal{V}(p)$ neighborhood of p , ω_p classification label of p .

Two potentials:

- To promote coherence with classification $\rightarrow V_1(k, j, q_{k,j}) = \log(q_{k,j})$;
- To promote spatial coherence (Potts-Markov potential) $\rightarrow V_2(k, z_{p'}) = \beta_1 \delta(k, z_{p'})$ with $\delta(\cdot, \cdot)$ Kronecker function.

Hierarchical model



Clustering (3)

Estimation of coefficients of **interaction between high-level and low-level information**:

$$\mathbf{q}_j \sim \text{Dir}(\mathbf{1}) \rightarrow \mathbf{q}_j | \mathbf{z}, \boldsymbol{\omega} \sim \text{Dir}(n_{1,j}, \dots, n_{K,j}) \quad \text{with} \quad n_{k,j} = \#\{p | z_p = k, \omega_p = j\}$$

In particular:

$$\begin{aligned} \mathbb{E}[q_{k,j} | \mathbf{z}, \boldsymbol{\omega}] &= \frac{n_{k,j}}{\sum_{i=1}^K n_{i,k}} \\ &= \mathbb{P}[z_p = k | \omega_p = j] \end{aligned}$$

Classification (1)

Classification rule with a Markov random field

$$P[\omega_p = j | \omega_{\mathcal{V}(p)}, c_p, \eta_p] \propto \exp \left(W_1(j, c_p, \eta_p) + \sum_{p' \in \mathcal{V}(p)} W_2(j, \omega_{p'}) \right)$$

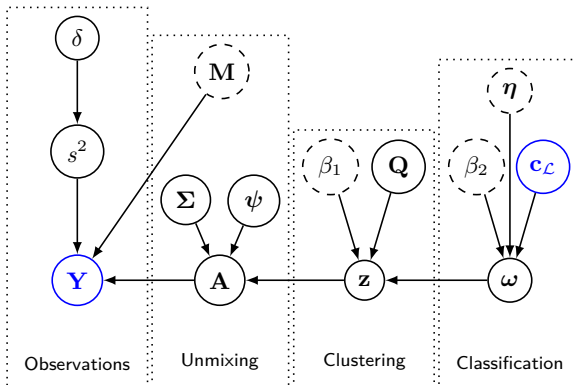
Two potentials:

- To promote coherence with labeled data

$$W_1(j, c_p, \eta_p) = \begin{cases} \begin{cases} \log(\eta_p), & \text{if } j = c_p \\ \log(\frac{1-\eta_p}{J-1}), & \text{otherwise} \end{cases} & \text{if } p \in \mathcal{L} \\ -\log(J) & \text{otherwise} \end{cases}$$

- To promote spatial coherence $\rightarrow W_2(j, \omega_{p'}) = \beta_2 \delta(j, \omega_{p'})$.

Hierarchical model



Classification (2)

Robust classification:

- $\eta_p \in (0, 1)$ the confidence in label c_p provided by user
- Possibility to correct labeled data when $\eta_p < 1$

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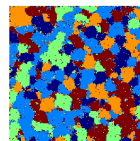
Conclusions and perspectives

Dataset

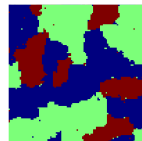
- 413 spectral bands
- $\text{SNR} = 30\text{dB}$
- Clustering generated with Potts-Markov MRF
- Classes created by aggregating several clusters
- Image 1: 3 clusters, 2 classes, 3 endmembers, 100x100px
- Image 2: 12 clusters, 5 classes, 9 endmembers, 200x200px



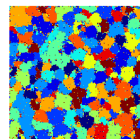
(a)



(b)



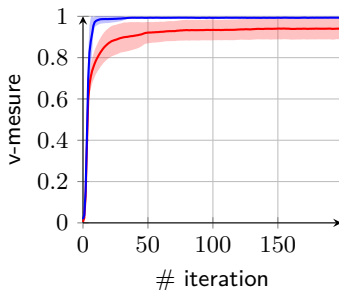
(c)



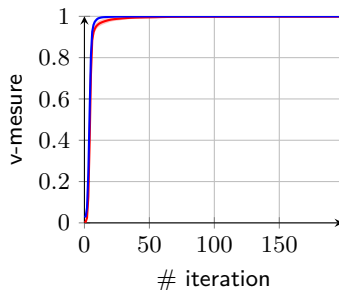
(d)

Classification map: (a) image 1, (b) image 2;
Clusters: (c) image 1, (d) image 2

Results



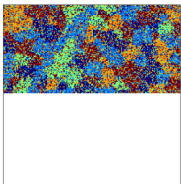
(a)



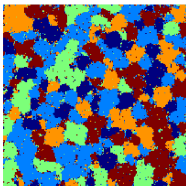
(b)

Proposed model in blue, model without classification stage (Eches *et al.*). (a) Clustering convergence for image 1, (b) Clustering convergence for image 2

Results



Provided labeled data



Classification obtained

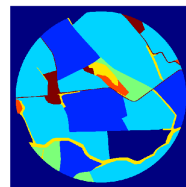
- Deterioration of labeled data (40% of error)
 - Confidence set to 60%
- ⇒ Correction of mislabeled pixels

Dataset

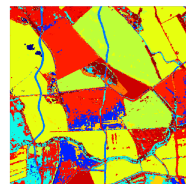
- 349 spectral bands
- 10 endmembers extracted with VCA
- 6 classes (straw cereal, summer crop, wooded area, artificial surfaces, bare soil, pasture)
- Top half of groundtruth provided as labeled data



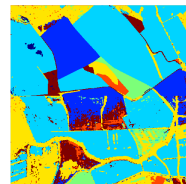
(a)



(b)



(c)



(d)

Muesli dataset: (a) colored composition of data, (b) groundtruth, (c) obtained clustering and (d) obtained classification

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Conclusions

- A new hierarchical Bayesian model
- Joint unmixing, clustering, classification
- Estimation of an interaction coefficient between high-level and low-level information
- Robustness to labeling error