

# Statistics and learning

## Statistical estimation

Emmanuel Rachelson and Matthieu Vignes

ISAE SupAero

Wednesday 18<sup>th</sup> September 2013

# How to retrieve 'lecture' support & practical sessions

LMS @ ISAE

or

My website

(clickable links)

# Things you have to keep in mind

Crux of the estimation

- Population, sample and statistics.

# Things you have to keep in mind

Crux of the estimation

- ▶ Population, sample and statistics.
- ▶ Concept of estimator of a parameter.

# Things you have to keep in mind

## Crux of the estimation

- ▶ Population, sample and statistics.
- ▶ Concept of estimator of a parameter.
- ▶ Bias, comparison of estimators, Maximum Likelihood Estimator.

# Things you have to keep in mind

## Crux of the estimation

- ▶ Population, sample and statistics.
- ▶ Concept of estimator of a parameter.
- ▶ Bias, comparison of estimators, Maximum Likelihood Estimator.
- ▶ Sufficient statistics, quantiles.

# Things you have to keep in mind

## Crux of the estimation

- ▶ Population, sample and statistics.
- ▶ Concept of estimator of a parameter.
- ▶ Bias, comparison of estimators, Maximum Likelihood Estimator.
- ▶ Sufficient statistics, quantiles.
- ▶ Interval estimation.

# Statistical estimation

Steps in estimation procedure:

- ▶ Consider a population (size  $N$ ) described by a random variable  $X$  (known or unknown distribution) with parameter  $\theta$ ,



# Statistical estimation

Steps in estimation procedure:

- ▶ Consider a population (size  $N$ ) described by a random variable  $X$  (known or unknown distribution) with parameter  $\theta$ ,
- ▶ a sample with  $n \leq N$  independent observations  $(x_1 \dots x_n)$  is extracted,

# Statistical estimation

Steps in estimation procedure:

- ▶ Consider a population (size  $N$ ) described by a random variable  $X$  (known or unknown distribution) with parameter  $\theta$ ,
- ▶ a sample with  $n \leq N$  independent observations  $(x_1 \dots x_n)$  is extracted,
- ▶  $\theta$  is estimated through a **statistic** (=function of  $X_i$ 's):  
 $\hat{\theta} = T(X_1 \dots X_n)$ .

# Statistical estimation

Steps in estimation procedure:

- ▶ Consider a population (size  $N$ ) described by a random variable  $X$  (known or unknown distribution) with parameter  $\theta$ ,
- ▶ a sample with  $n \leq N$  independent observations  $(x_1 \dots x_n)$  is extracted,
- ▶  $\theta$  is estimated through a **statistic** (=function of  $X_i$ 's):  
 $\hat{\theta} = T(X_1 \dots X_n)$ .

Note: independence is true only if drawing is made with replacement.  
Without replacement, the approximation is ok if  $n \ll N$ .

# Statistical estimation

Steps in estimation procedure:

- ▶ Consider a population (size  $N$ ) described by a random variable  $X$  (known or unknown distribution) with parameter  $\theta$ ,
- ▶ a sample with  $n \leq N$  independent observations  $(x_1 \dots x_n)$  is extracted,
- ▶  $\theta$  is estimated through a **statistic** (=function of  $X_i$ 's):  
 $\hat{\theta} = T(X_1 \dots X_n)$ .

Note: independence is true only if drawing is made with replacement. Without replacement, the approximation is ok if  $n \ll N$ .

## Mean estimation

Estimate the average life span of a bulb...

# Point estimation of a parameter

## Recall

$n$  realisations of random variables iid  $(X_1 \dots X_n)$  are available. Some parameters can be of interest. Direct computation not feasible so estimation needed. **Objective** here: tools and maths grounds for estimation.

# Point estimation of a parameter

## Recall

$n$  realisations of random variables iid  $(X_1 \dots X_n)$  are available. Some parameters can be of interest. Direct computation not feasible so estimation needed. **Objective** here: tools and maths grounds for estimation.

## Definitions

- ▶ **Statistical model:** definition of a probability distribution  $P_\theta$  (joint if discrete rv and density if continuous rv), with  $\theta$  is a ( $p$ -vector of) unknown parameter(s).
- ▶ **Statistic:**  $T : \mathbb{R}^n \rightarrow \mathbb{R}^{(p)}, (x_i)_{i=1\dots n} \mapsto T(x_1 \dots x_n)$ . Examples: empirical mean or variance (known/unknown mean).

# Estimator, bias, comparison

## Exercise

Lift can bear 1,000 *kg*. User weight  $\sim \mathcal{N}(75, 16^2)$ .

- ▶ Max. number of people allowed in it if  $P(\text{lift won't take off}) = 10^{-6}$  ?
- ▶ Lift manufacturer allows 11 people inside.  $P(\text{overweight}) = ??$

# Estimator, bias, comparison

## Exercise

Lift can bear 1,000 kg. User weight  $\sim \mathcal{N}(75, 16^2)$ .

- ▶ Max. number of people allowed in it if  $P(\text{lift won't take off}) = 10^{-6}$  ?
- ▶ Lift manufacturer allows 11 people inside.  $P(\text{overweight}) = ??$

## Definitions

- ▶ **Estimator** of an unknown parameter  $\theta$ : a statistic denoted  $\hat{\theta}$  (observed values are approximations of  $\theta$ ). The **bias** associated to  $\hat{\theta}$  is  $E[\hat{\theta}] - \theta$  (if = 0,  $\hat{\theta}$  is said to be unbiased). Ex: (exercices) (i) the empirical mean is an unbiased estimator for the (theoretical) mean. (ii)  $S_n^2 := \frac{\sum_{i=1}^n (X_i - \bar{X})^2}{n}$  is a biased estimator for  $\sigma^2$ .
- ▶  $\hat{\theta}$  is **asymptotically unbiased** if  $\lim_{n \rightarrow \infty} E[\hat{\theta}] = \theta$ .
- ▶  $\hat{\theta}_1$  and  $\hat{\theta}_2$ : 2 unbiased estimator for  $\theta$ ;  $\hat{\theta}_1$  is better than  $\hat{\theta}_2$  if  $Var(\hat{\theta}_1) < Var(\hat{\theta}_2)$ ; in practice,  $\hat{\theta}_1$  converges faster than  $\hat{\theta}_2$ .



# Application break

## Estimating the duration of a traffic light

$\theta > 0$  is the actual duration of a traffic light. Unknown. We observe a sample  $t_1 \dots t_n$ , where  $t_i$  is the waiting time of driver  $i$ .

1. What is a good modelling for  $T_i$ 's ? Density ? Mean and variance ?
2. If  $\bar{T} = \frac{1}{n} \sum_{i=1}^n T_i$ , what is  $E[\bar{T}]$  ?  $\text{var}(\bar{T})$  ? Can you use  $\bar{T}$  to build an unbiased estimator of  $\theta$  ? Establish its probability convergence.
3. Let  $M_n = \sup_i T_i$ . Compute the cumulative probability function of  $M_n$  ? Density ? Mean and variance ? Plot the cpf for  $n = 3$ ,  $n = 30$  and interpret. Use  $M_n$  to build an unbiased probability-convergent estimator of  $\theta$ .
4. Compare the variances of both estimators. Which one would you use to estimate  $\theta$  ?
5. Numerical application for  $n = 3$  and  $(t_1, t_2, t_3) = (2, 24, 13)$ .

# Convergence of estimators

Def:  $\hat{\theta}$  converges in probability towards  $\theta$  if  $\forall \epsilon > 0, P(|\hat{\theta} - \theta| < \epsilon) \rightarrow_n 1$ .

# Convergence of estimators

Def:  $\hat{\theta}$  converges in probability towards  $\theta$  if  $\forall \epsilon > 0, P(|\hat{\theta} - \theta| < \epsilon) \rightarrow_n 1$ .

## Theorem

*An (asymptotically) unbiased estimator s.t.  $\lim_n \text{Var}(\hat{\theta}) = 0$  converges in probability towards  $\theta$ .*

# Convergence of estimators

Def:  $\hat{\theta}$  converges in probability towards  $\theta$  if  $\forall \epsilon > 0, P(|\hat{\theta} - \theta| < \epsilon) \rightarrow_n 1$ .

## Theorem

*An (asymptotically) unbiased estimator s.t.  $\lim_n \text{Var}(\hat{\theta}) = 0$  converges in probability towards  $\theta$ .*

## Theorem

*An unbiased estimator  $\hat{\theta}$  with the following technical regularity hypotheses (H1-H5) verifies  $\text{Var}(\hat{\theta}) > V_n(\theta)$ , with the Cramer-Rao bound*

*$V_n(\theta) := (-E[\frac{\partial^2 \log f(X_1 \dots X_n; \theta)}{\partial \theta^2}])^{-1}$  (inverse of Fisher information).*

*(H1) the support  $D := \{X, f(x; \theta) > 0\}$  does not depend upon  $\theta$ .*

*(H2)  $\theta$  belongs to an open interval  $I$ .*

*(H3) on  $I \times D$ ,  $\frac{\partial f}{\partial \theta}$  and  $\frac{\partial^2 f}{\partial \theta^2}$  exist and are integrable over  $x$ .*

*(H4)  $\theta \mapsto \int_A f(x; \theta) dx$  has a second order derivative ( $x \in I, A \in \mathcal{B}(\mathbb{R})$ )*

*(H5)  $(\frac{\partial \log f(X; \theta)}{\partial \theta})^2$  is integrable.*

# Application to the estimation of a $|\mathcal{N}|$

## Definition

An unbiased estimator  $\hat{\sigma}$  for  $\theta$  is **efficient** if its variance is equal to the Cramer-Rao bound. It is the best possible among unbiased estimators.

# Application to the estimation of a $|\mathcal{N}|$

## Definition

An unbiased estimator  $\hat{\theta}$  for  $\theta$  is **efficient** if its variance is equal to the Cramer-Rao bound. It is the best possible among unbiased estimators.

## Exercise

Let  $(X_i)_{i=1\dots n}$  iid rv  $\sim \mathcal{N}(m, \sigma^2)$ .  $Y_i := |X_i - m|$  is observed.

- ▶ Density of  $Y_i$  ? Compute  $E[Y_i]$  ? Interpretation compared to  $\sigma$  ?
- ▶ Let  $\hat{\sigma} := \sum_i a_i Y_i$ . If we want  $\hat{\sigma}$  to be unbiased, give a constraint on  $(a_i)$ 's. Under this constraint, show that  $Var(\hat{\sigma})$  is minimum iff all  $a_i$  are equal. In this case, give the variance.
- ▶ Compare the Cramer-Rao bound to the above variance. Is the built estimator efficient ?

# Likelihood function

## Definition

The likelihood of a rv  $\mathbf{X} = (X_1 \dots X_n)$  is the function  $L$ :

$$L : \mathbb{R}^n \times \Theta \longrightarrow \mathbb{R}^+ \\ (x, \theta) \longmapsto L(x; \theta) := \begin{cases} f(x; \theta), \text{ the density of } \mathbf{X} \\ \text{or} \\ P_\theta(X_1 = x_1 \dots X_n = x_n), \text{ if } \mathbf{X} \text{ discrete} \end{cases}$$

# Likelihood function

## Definition

The likelihood of a rv  $\mathbf{X} = (X_1 \dots X_n)$  is the function  $L$ :

$$L : \mathbb{R}^n \times \Theta \longrightarrow \mathbb{R}^+ \\ (x, \theta) \longmapsto L(x; \theta) := \begin{cases} f(x; \theta), \text{ the density of } \mathbf{X} \\ \text{or} \\ P_\theta(X_1 = x_1 \dots X_n = x_n), \text{ if } \mathbf{X} \text{ discrete} \end{cases}$$

## Examples

- ▶  $X_i$  Gaussian iid rv:

$$L(x; \theta) = \prod_i f(x_i; \theta) = \left( \frac{1}{\sigma \sqrt{2\pi}} \right)^n \exp \left[ -\frac{1}{2} \sum_i \left( \frac{x_i - m}{\sigma} \right)^2 \right]$$

- ▶  $X_i$  Bernouilli iid rv:  $L(x; \theta) = p^{\sum x_i} (1 - p)^{n - \sum x_i}$



# Maximum likelihood estimation (MLE)

## Definition

$$\hat{\theta}_{MLE} := \arg \max_{\theta \in \Theta} (\log) L(x_1 \dots x_n; \theta)$$

Interpretation:  $\hat{\theta}_{MLE}$  is the parameter value that gives maximum probability to the observed values or random variables...

# Maximum likelihood estimation (MLE)

## Definition

$$\hat{\theta}_{MLE} := \arg \max_{\theta \in \Theta} (\log) L(x_1 \dots x_n; \theta)$$

Interpretation:  $\hat{\theta}_{MLE}$  is the parameter value that gives maximum probability to the observed values or random variables...

*Remark:* the EMV does not always exists (possible alternatives: least square or moments). When it exists, it is not necessarily unique, can be biased or not efficient. However...

# Maximum likelihood estimation (MLE)

## Definition

$$\hat{\theta}_{MLE} := \arg \max_{\theta \in \Theta} (\log) L(x_1 \dots x_n; \theta)$$

Interpretation:  $\hat{\theta}_{MLE}$  is the parameter value that gives maximum probability to the observed values or random variables...

*Remark:* the EMV does not always exists (possible alternatives: least square or moments). When it exists, it is not necessarily unique, can be biased or not efficient. However...

## Theorem

- ▶  $\hat{\theta}_{MLE}$  is asymptotically unbiased and efficient.
- ▶  $\frac{\hat{\theta}_{MLE} - \theta}{V_n(\theta)} \longrightarrow_n \mathcal{N}(0, 1)$ , where  $V_n(\theta)$  is the Cramer-Rao bound.
- ▶  $\hat{\theta}_{MLE}$  converges to  $\theta$  in squared mean.

# Maximum likelihood estimation (MLE)

## Definition

$$\hat{\theta}_{MLE} := \arg \max_{\theta \in \Theta} (\log) L(x_1 \dots x_n; \theta)$$

Interpretation:  $\hat{\theta}_{MLE}$  is the parameter value that gives maximum probability to the observed values or random variables...

*Remark:* the EMV does not always exists (possible alternatives: least square or moments). When it exists, it is not necessarily unique, can be biased or not efficient. However...

## Theorem

- ▶  $\hat{\theta}_{MLE}$  is asymptotically unbiased and efficient.
- ▶  $\frac{\hat{\theta}_{MLE} - \theta}{V_n(\theta)} \longrightarrow_n \mathcal{N}(0, 1)$ , where  $V_n(\theta)$  is the Cramer-Rao bound.
- ▶  $\hat{\theta}_{MLE}$  converges to  $\theta$  in squared mean. 'MLE for a proportion' exercice ? Mean and variance estimation of  $\mathcal{N}(\mu, \sigma)$ .

# Sufficient statistic

## Remark/definition

Any realisation  $(x_i)$  of a rv  $X$ , unknown distribution but parameterised by  $\theta$ , from a sample contains information on  $\theta$ . If the statistic summarises all possible information from the sample, it is **sufficient**. In other words "no other statistic which can be calculated from the same sample provides any additional information as to the value of the parameter" (Fisher 1922)

In mathematical terms:  $P(X = x|T = t, \theta) = P(X = x|T = t)$

# Sufficient statistic

## Remark/definition

Any realisation  $(x_i)$  of a rv  $X$ , unknown distribution but parameterised by  $\theta$ , from a sample contains information on  $\theta$ . If the statistic summarises all possible information from the sample, it is **sufficient**. In other words "no other statistic which can be calculated from the same sample provides any additional information as to the value of the parameter" (Fisher 1922)

In mathematical terms:  $P(X = x|T = t, \theta) = P(X = x|T = t)$

## Theorem (Fisher-Neyman)

$T(X)$  is sufficient if there exist 2 functions  $g$  and  $h$  s.t.

$$L(x; \theta) = g(t; \theta)h(x)$$

*Implication:* in the context of MLE, 2 samples yielding the same value for  $T$  yield the same inferences about  $\theta$ . (dep. on  $\theta$  is only in conjunction with  $T$ ).

# Sufficient statistic

An example

## Sufficiency of an estimator of a proportion

Quality control in a factory:  $n$  items drawn with replacement to estimate  $p$  the proportion of faulty items.  $X_i = 1$  if item  $i$  is cracked, 0 otherwise. Show that the 'classical' estimator for  $p$ ,  $\frac{1}{n} \sum_{i=1}^n X_i$  is sufficient.

# Quantiles

## Definition

The cumulative distribution function  $F$  ( $F(x) = \int_{-\infty}^x f(t)dt$ , with  $f$  density of  $X$ ) is a non-decreasing function  $\mathbb{R} \rightarrow [0; 1]$ . Its inverse  $F^{-1}$  is called the quantile function.  $\forall \beta \in ]0; 1[$ , the  $\beta$ -quantile is defined by  $F^{-1}(\beta)$ .



# Quantiles

## Definition

The cumulative distribution function  $F$  ( $F(x) = \int_{-\infty}^x f(t)dt$ , with  $f$  density of  $X$ ) is a non-decreasing function  $\mathbb{R} \rightarrow [0; 1]$ . Its inverse  $F^{-1}$  is called the quantile function.  $\forall \beta \in ]0; 1[$ , the  $\beta$ -quantile is defined by  $F^{-1}(\beta)$ .

In particular:  $P(X \leq F^{-1}(\beta)) = \beta$  and  $P(X \geq F^{-1}(\beta)) = 1 - \beta$

# Quantiles

## Definition

The cumulative distribution function  $F$  ( $F(x) = \int_{-\infty}^x f(t)dt$ , with  $f$  density of  $X$ ) is a non-decreasing function  $\mathbb{R} \rightarrow [0; 1]$ . Its inverse  $F^{-1}$  is called the quantile function.  $\forall \beta \in ]0; 1[$ , the  $\beta$ -quantile is defined by  $F^{-1}(\beta)$ .

In particular:  $P(X \leq F^{-1}(\beta)) = \beta$  and  $P(X \geq F^{-1}(\beta)) = 1 - \beta$

In practice, either quantile are read from tables: either  $F$  or  $F^{-1}$  (old-fashioned) or they are computed using statistics softwares on computers (`qnorm`, `qbinom`, `qpois`, `qt`, `qchisq`, etc. in R).

Quantile for the Gaussian distribution will (most of the time) be denoted  $z_\beta$ . For Student distribution  $t_\beta$  and so on.

By the way: what are  $\chi^2$  and Student distribution ?

# Interval estimation

$\hat{\theta}$ : a point estimation of  $\theta$ ; even in favourable situations, it is very unlikely that  $\hat{\theta} = \theta$ . How close is it ? Could an interval that contains the true value of  $\theta$  with say a high probability (low error) be built ? Not too big (informative), but not too restricted neither (for the true value has a great chance of being in it).

# Interval estimation

$\hat{\theta}$ : a point estimation of  $\theta$ ; even in favourable situations, it is very unlikely that  $\hat{\theta} = \theta$ . How close is it ? Could an interval that contains the true value of  $\theta$  with say a high probability (low error) be built ? Not too big (informative), but not too restricted neither (for the true value has a great chance of being in it).

Typically, a  $1/\sqrt{n}$ -neighbourhood of  $\hat{\theta}$  will do the job. It is much more useful than many digits in an estimator to give an interval with the associated error.

# Interval estimation

$\hat{\theta}$ : a point estimation of  $\theta$ ; even in favourable situations, it is very unlikely that  $\hat{\theta} = \theta$ . How close is it ? Could an interval that contains the true value of  $\theta$  with say a high probability (low error) be built ? Not too big (informative), but not too restricted neither (for the true value has a great chance of being in it).

Typically, a  $1/\sqrt{n}$ -neighbourhood of  $\hat{\theta}$  will do the job. It is much more useful than many digits in an estimator to give an interval with the associated error.

## Definition

1. A confidence interval  $\hat{I}_n$  is defined by a couple of estimators:  
 $\hat{I}_n = [\hat{\theta}_1; \hat{\theta}_2]$ .
2. its associated confidence level  $1 - \alpha$  ( $\alpha \in [0; 1]$ ) is s.t.  
 $P(\theta \in \hat{I}_n) \geq 1 - \alpha$ .
3.  $\hat{I}_n$  is asymptotically of level at least  $1 - \alpha$  if  $\forall \epsilon > 0, \exists N_e$  s.t.  
 $P(\theta \in \hat{I}_n) \geq 1 - \alpha - \epsilon$  for  $n \geq N_e$ .

# Confidence intervals you need to know

a partial typology

- ▶  $X_i \sim \mathcal{N}(m, \sigma^2)$ , with  $\sigma^2$  known, then  $I(m) = [\bar{x} \pm z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}}]$ .
- ▶ when  $\sigma^2$  is unknown, it becomes  $I(m) = [\bar{x} \pm t_{n-1; 1-\alpha/2} \frac{s_{n-1}}{\sqrt{n}}]$ ,  
with  $s_{n-1}^2 := \frac{\sum (x_i - \bar{x})^2}{n-1}$  and  $t_{n-1; 1-\alpha/2}$  the quantile of a Student distribution with  $n-1$  degrees of freedom (df). Note that  $t_{n-1; 1-\alpha/2} \simeq_n z_{1-\alpha/2}$ .
- ▶ if Gaussianity is lost, we can only derive asymptotic confidence intervals.
- ▶ as for  $\sigma^2$ : if  $m$  is known  $I_\alpha = [\frac{\widehat{n\sigma^2}}{\chi_{n; 1-\alpha/2}^2}; \frac{\widehat{n\sigma^2}}{\chi_{n; \alpha/2}^2}]$
- ▶ when  $m$  is unknown:  $I_\alpha = [\frac{(n-1)S_{n-1}^2}{\chi_{n-1; 1-\alpha/2}^2}; \frac{(n-1)S_{n-1}^2}{\chi_{n-1; \alpha/2}^2}]$
- ▶ confidence interval for a proportion: exercices (if time permits)
- ▶ for other distributions: use the Cramer-Rao bound !

# Next time

## Multivariate descriptive statistics !

# Next time

## Multivariate descriptive statistics !

Some notions of (advanced) algebras will be needed. *E.g.* Matrices, operations, inverse, rank, projection, metrics, scalar product, eigenvalues/vectors, matrix norm, matrix approximation . . . .