

# Estimation of the conditional cumulative distribution function from current status data by model selection

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- 1 Current status data
- 2 Model selection (univariate framework)
- 3 Adaptive estimation of the conditional c.d.f from current status data
- 4 Results on simulated data

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- **Current status data** :

$$\begin{cases} C \text{ observation time} \\ \Delta = \mathbb{1}_{T \leq C} \\ Z \text{ covariate} \end{cases}$$

↪ Require assumptions on  $\mathbb{P}[C|T, Z]$  (most usual :  $T \perp\!\!\!\perp C|Z$ ).

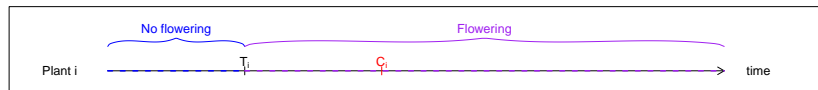
↪ Vocabulary of survival analysis :  $T$  is the time of death and  $\Delta$  is the current status (dead or alive) at the observation time.

# An example of current status data

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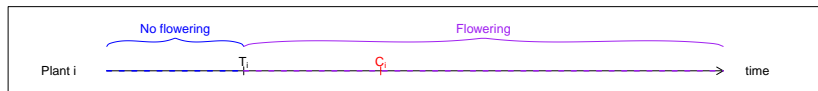
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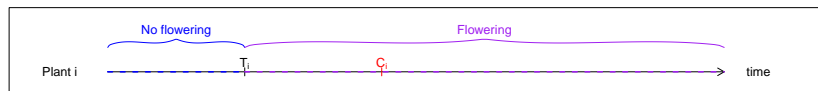
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- $\Delta_i$  indicates if  $T_i$  lies in  $[0, C_i]$  or  $[C_i, +\infty[$ . Current status data framework is also called *interval censoring "case 1"*.

## Brief review on estimation from current status data

$(T_i)_{i=1,\dots,n}$  unobserved,  $(C_i, \Delta_i = \mathbb{1}_{T_i \leq C_i}, Z_i)_{i=1,\dots,n}$  observations

- **Non Parametric Maximum Likelihood Estimator** of the c.d.f. The likelihood only depends on the value of the c.d.f. at the observation points  $(C_i)$ , and admit a unique minimiser over  $\{h : \mathbb{R}_+ \mapsto [0, 1]\}$  with an explicit expression.
- **Quantile regression** is based on the invariance of quantiles by monotone transformations, and the observation that the following function is decreasing.

$$\begin{array}{lcl} h : & x & \mapsto \mathbb{1}_{x \leq C} \\ & T & \mapsto \Delta \end{array}$$

- **Inverse Probability of censoring Weighted Estimator (IPWE)** : the risk  $\mathbb{E}[L((T, Z), h)]$  is estimated by an empirical contrast with observation  $\Delta_i$  weighted by the inverse of the "probability to be observed" at  $C_i$  :  $f_C(C_i)$ .
- **Semi-parametric models** : the distribution of  $T$  is linearly related to the covariates  $Z$

$$\mathbb{P}[T|Z] = \phi(T, \langle \beta, Z \rangle)$$

- **Dependent censoring** : models on the joint distribution of  $T$  and  $C$

# Framework of this presentation

- We consider an i.i.d. sample  $(T_i, C_i, Z_i)_{i=1, \dots, n}$  and the observation sample

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- ◇  $\Delta_i = \mathbb{1}_{T_i \leq C_i}$ .
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  - ◊  $T_i \perp\!\!\!\perp C_i | Z_i$
- **Goal** : Estimate the conditional c.d.f. of  $T_i$  given  $Z_i$

$$F(t, z) = \mathbb{P}[T_i \leq t | Z_i = z]$$

on a compact  $A = A_1 \times A_2 \subset \mathbb{R}_+ \times \mathbb{R}$ .

# Least-square contrast

- Let  $(C_i, Z_i, \Delta_i)_{i=1, \dots, n}$  the i.i.d. observation sample with  $\Delta_i = \mathbb{1}_{T_i \leq C_i}$ .
- By definition of  $\Delta_i$ ,

$$\begin{aligned}\mathbb{E}[\Delta_i | C_i = c, Z_i = z] &= \mathbb{E}[\mathbb{1}_{T_i \leq C_i} | C_i = c, Z_i = z] \\ &= \mathbb{P}[T_i \leq c | Z_i = z] \\ &= F(c, z)\end{aligned}$$

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- **Model selection** :

- ◇ build a collection of estimators on finite dimensional linear subspaces of  $L^2(A)$  called *models*
- ◇ select a model by a data-driven criterion.

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- Consider an empirical contrast  $\gamma_n : L^2(I) \mapsto \mathbb{R}$  such that

$$\mathbb{E}[\gamma_n(h)] = \|F - h\|_0^2 + cte$$

with  $cte$  independent of  $h$ .

# Collection of estimators

- Consider a collection  $\mathcal{M}_n = \{S_m, m \in I_n\}$  of finite dimensional linear subspaces  $L^2(I)$  called **models** :

$$S_m = \text{vect}\{\phi_1^m, \dots, \phi_{D_m}^m\} = \left\{ h = \sum_{k=1}^{D_m} a_k \phi_k^m, (a_1, \dots, a_{D_m}) \in \mathbb{R}^{D_m} \right\}$$

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- Once the collection  $\mathcal{M}_n$  fixed, "model" refers to either  $m$  or  $S_m$ .
- For each  $m \in I_n$ , let

$$\hat{F}_m = \arg \min_{h \in S_m} \gamma_n(h) = \sum_{k=1}^{D_m} \hat{a}_k^m \phi_k^m$$

↔ For a given model  $S_m$ , **the estimation of  $F$  reduces to estimate a finite number of parameters** ( $\hat{a}_k^m$ ).

## How to choose an estimator among the collection $\{\hat{F}_m, m \in I_n\}$ ?

- Oracle : best model in the collection

$$m_{oracle} = \arg \min_{m \in I_n} \mathbb{E} \left[ \|\hat{F}_m - F\|_0^2 \right]$$

- Oracle unknown (depends on the true function  $F$ )
- Idea : estimate  $\mathbb{E} \left[ \|\hat{F}_m - F\|_0^2 \right]$  up to a constant independent of  $m$ .

**Bias-variance decomposition.** Let  $F_m = \arg \min_{h \in S_m} \|h - F\|_0^2 = \arg \min_{h \in S_m} \mathbb{E}[\gamma_n(h)]$  the  $\|\cdot\|_0$ -projection of  $F$  on  $S_m$ .

Thus  $\langle \underbrace{\hat{F}_m - F_m}_{\in S_m}, \underbrace{F_m - F}_{\in S_m^\perp} \rangle_0 = 0$  therefore

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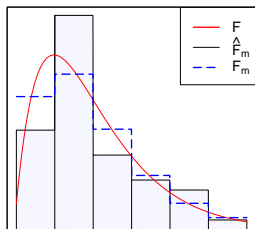
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- **Model selection estimator :**  $\boxed{\hat{F}_{\hat{m}}}$

# Bias and variance

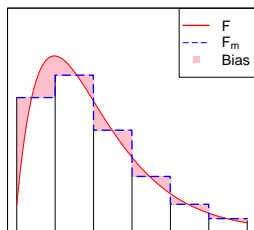
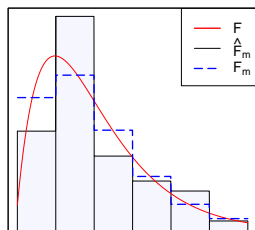
*Ex : density estimation from an i.i.d. sample by histogram with 6 bins ( $D_m = 6$ )*





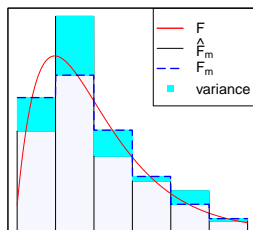
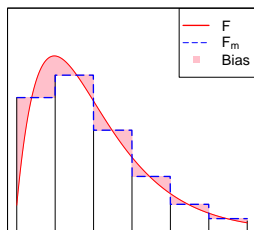
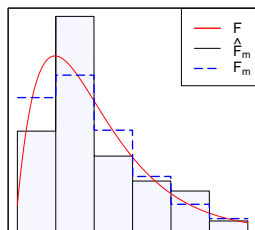
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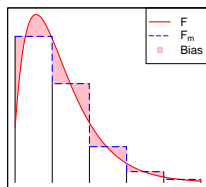
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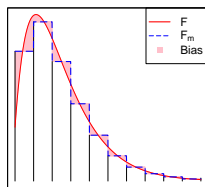


**Bias-variance compromise.** As the dimension  $D_m$  increases

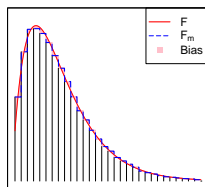
- ◇ Bias  $\|F_m - F_m\|_0^2$  decreases
- ◇ Variance  $\mathbb{E}[\|\hat{F}_m - F_m\|_0^2] \leq AD_m/n$  increases



$D_m = 5$

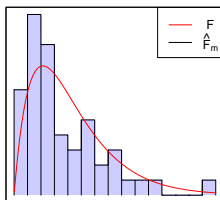
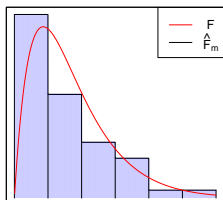


$D_m = 10$

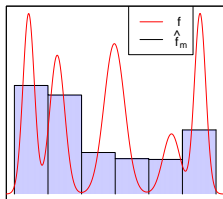


$D_m = 30$

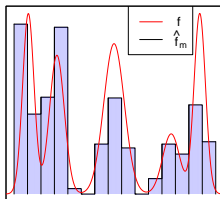
The dimension of the optimal model increases as the regularity of  $F$  decreases.



← More smooth  $F$



$D_m = 6$



$D_m = 20$

← Less smooth  $F$

## Result : oracle inequality

The risk of the model selection estimator  $\hat{F}_{\hat{m}}$  satisfies :

$$\mathbb{E} \left[ \|\hat{F}_{\hat{m}} - F\|_0^2 \right] \leq C_0 \inf_{m \in I_n} \left\{ \|F - F_m\|_0^2 + A \frac{D_m}{n} \right\} \quad (1)$$

- Proof based on concentration inequalities [Talagrand]
- Optimality among the collection of estimators
- $AD_m/n$  is only an upper-bound of the variance
- More general optimality : minimax rate.

# Rate of convergence over regularity classes

- Consider **classes of regularity**  $\mathcal{H}^\beta$  s.t. for suitable approximation spaces  $S_m$  :

$$\inf_{h \in S_m} \|h - F\|_0 \leq C_0 D_m^{-\beta} \quad \forall F \in \mathcal{H}^\beta$$

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$$\inf_{h \in S_m} \|h - F\|_0 \leq C_0 D_m^{-\beta} \quad \forall F \in \mathcal{H}^\beta$$

- If  $F \in \mathcal{H}^\beta$ , the bias/variance sum for a model  $S_m$  is upper-bounded by

$$\underbrace{D_m^{-2\beta}}_{\searrow \text{ as } D_m \nearrow} + \underbrace{\theta A \frac{D_m}{n}}_{\nearrow \text{ as } D_m \nearrow}$$

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- The **bias-variance compromise** is achieved with  $D_m \propto n^{1/(2\beta+1)}$  and the rate of convergence = is  $n^{-2\beta/(2\beta+1)}$



# Minimax rate of convergence

- **Minimax lower bounds.** We prove that  $n^{-2\beta/(2\beta+1)}$  is the **minimax rate of convergence** over  $\mathcal{H}^\beta$  that is the rate of convergence of the best possible estimator in a given context (regression, current status) based on a  $n$ -sample for functions in  $\mathcal{H}^\beta$  :

$$\inf_{\hat{F}_n} \sup_{F \in \mathcal{H}^\beta} \mathbb{E} \left[ \|\hat{F}_n - F\|_0^2 \right] n^{2\beta/(2\beta+1)} \geq \kappa_1$$

↔ Computing based on maximum coverage of  $\mathbb{R}^n$ -balls.

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- Therefore, the model selection estimator is minimax

$$\kappa_1 \leq \inf_{\hat{F}_n} \sup_{F \in \mathcal{C}^\beta} \mathbb{E} \left[ \|\hat{F}_n - F\|_0^2 \right] n^{2\beta/(2\beta+1)} \leq \mathbb{E} \left[ \|\hat{F}_m - F\|_0^2 \right] n^{2\beta/(2\beta+1)} \leq \kappa_0$$

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- $\hat{F}_{\hat{m}}$  is called **adaptive** as it adapts to the unknown regularity of  $F$ .

# Summary

- Define a collection of finite dimensional linear subspaces of  $L^2$  called **models**
- Compute a **collection of estimators** by minimisation of a contrast over the collection of models
- Estimate the bias-variance sum of each estimator and select the model
- **Oracle inequality** : the risk of the selected model is smaller than the risk of the best model up to a multiplicative constant
- More general optimality : **minimax rate of convergence** over classes of regularity
- **Comment** : choice of the approximation basis used to build the collection of models  $\mathcal{M}_m$ 
  - ◊ The nature of the basis affect the bias
  - ◊ Bases are associated to regularity classes which allow control of the bias (global/local regularity)
  - ◊ Choice may be guided by desired property of the estimator (differentiability, localisation on an interval...)

- 1 Current status data
- 2 Model selection (univariate framework)
- 3 Adaptive estimation of the conditional c.d.f from current status data**
- 4 Results on simulated data

# Reminder of the framework

- Consider  $(T_i, Z_i)_{i=1, \dots, n}$  i.i.d with  $T_i \in \mathbb{R}_+$ ,  $Z_i \in \mathbb{R}$  and  $T_i$  **unobserved**.

- **Observations**

$$(C_i, \Delta_i = \mathbb{1}_{T_i \leq C_i}, Z_i)_{i=1, \dots, n}$$

with  $(C_i)_{i=1, \dots, n}$  i.i.d. positive and  $C_i \perp\!\!\!\perp T_i | Z_i$ .

- We want to estimate the **conditional c.d.f.** of  $T_i$

$$F(t, z) = \mathbb{P}[T_i \leq t | Z_i = z]$$

on a compact  $A = A_1 \times A_2 \subset \mathbb{R}_+ \times \mathbb{R}$ .

- As  $\mathbb{E}[\Delta_i | C_i, Z_i] = F(C_i, Z_i)$ , we consider the **least square contrast**

$$\gamma_n(h) = \frac{1}{n} \sum_{i=1}^n (\Delta_i - h(C_i, Z_i))^2, \quad h : A \mapsto \mathbb{R}$$

# Collection of models on $A_1 \times A_2$

- Consider two collections of models on  $A_1$  and  $A_2$  :

$$\mathcal{M}_n^{(j)} = \{S_{m_j}^{(j)}, m_j \in I_n^{(j)}\}, \quad j = 1, 2 \quad \text{and}$$

$(\phi_k^{m_1})_{k=1, \dots, D_{m_1}^{(1)}}$  and  $(\psi_k^{m_2})_{k=1, \dots, D_{m_2}^{(2)}}$  orthonormal basis of  $S_{m_1}^{(1)}$  and  $S_{m_2}^{(2)}$ .

- Linear subspaces of  $L^2(A_1 \times A_2)$  built as **tensor products** of the linear subspaces of  $L^2(A_1)$  and  $L^2(A_2)$ . For every  $m = (m_1, m_2)$ , let

$$S_m = S_{m_1}^{(1)} \otimes S_{m_2}^{(2)} = \left\{ (t, z) \in A \mapsto \sum_{k=1}^{D_{m_1}^{(1)}} \sum_{\ell=1}^{D_{m_2}^{(2)}} a_{k,\ell}^m \phi_k^{m_1}(t) \psi_\ell^{m_2}(z), (a_{k,\ell}^m)_{k,\ell} \in \mathbb{R}^{D_m} \right\}$$

linear subspace of  $L^2(A)$  of dimension  $D_m = D_{m_1}^{(1)} D_{m_2}^{(2)}$

- Finally, the collection of model on  $L^2(A)$  is

$$\mathcal{M}_n = \{S_m, m \in I_n = I_n^{(1)} \times I_n^{(2)}\}$$

**Example :** Let  $A_1 = A_2 = [0, 1]$ , and

$$\begin{cases} S_{m_1}^{(1)} = \text{regular histograms with } D_1 \text{ bins on } [0, 1] = \text{vect} \left\{ \mathbb{1}_{J_k^1}, k = 1, \dots, D_1 \right\} \\ S_{m_2}^{(2)} = \text{regular histograms with } D_2 \text{ bins on } [0, 1] = \text{vect} \left\{ \mathbb{1}_{J_\ell^2}, \ell = 1, \dots, D_2 \right\} \end{cases}$$

Then

$$S_{m_1}^{(1)} \otimes S_{m_2}^{(2)} = \text{vect} \left\{ \mathbb{1}_{J_k^1 \times J_\ell^2}, k = 1, \dots, D_1, \ell = 1, \dots, D_2 \right\}$$

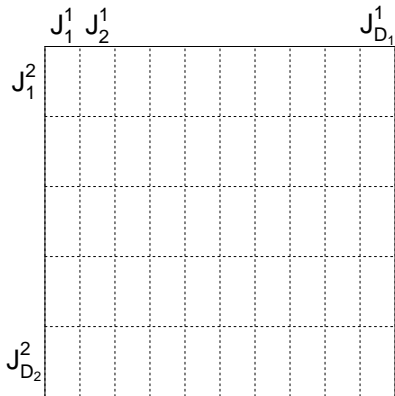


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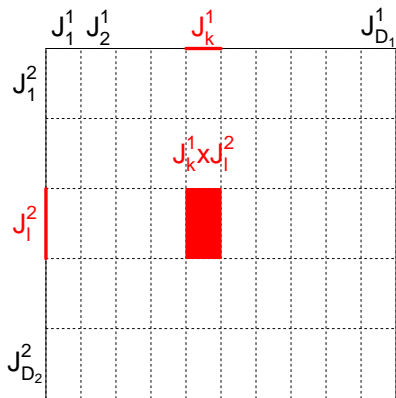


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# Least square estimators

$$\gamma_n(h) = \frac{1}{n} \sum_{i=1}^n (\Delta_i - h(C_i, Z_i))^2$$

- For every  $S_m \in \mathcal{M}_n$ ,

$$\hat{F}_m = \arg \min_{h \in S_m} \gamma_n(h)$$

- $\hat{F}_m$  is **uniquely defined on the observations design**  $(\mathbf{C}, \mathbf{Z})$

[notation :  $\mathbf{C} = (C_1, \dots, C_n)$  and  $\mathbf{\Delta} = (\Delta_1, \dots, \Delta_n)$ ]

- **Collection of estimators**  $\{\hat{F}_m, m \in I_n\}$ .

We consider two risks to quantify the distance between  $F$  and an estimator  $\hat{F}_m$

- **The empirical risk** : we show that

$$\mathbb{E}[\gamma_n(h)|\mathbf{C}, \mathbf{Z}] = \|h - F\|_n^2 + cte \quad \text{with} \quad \|h_0\|_n^2 = \frac{1}{n} \sum_{i=1}^n (h_0(C_i, Z_i))^2$$

thus we consider the risk

$$\mathbb{E} \left[ \|\hat{F}_m - F\|_n^2 | \mathbf{C}, \mathbf{Z} \right]$$

↪ Evaluate the quality of estimation at the observations : naturally arise in least-square

- **The integrated risk**

$$\mathbb{E} \left[ \|\hat{F}_m - F\|^2 \right] \quad \text{with} \quad \|\cdot\| \text{ the } L^2\text{-norm}$$

↪ More general control

↪ Requires additional assumption to control the behaviour of the function out of the observations.

We will first state an upper bound for empirical risk, then derive the result for the  $L^2$ -risk.

- **Bias-variance decomposition** for the empirical risk : let

$$F_m = \arg \min_{h \in S_m} \|F - h\|_n^2,$$

$$\mathbb{E} \left[ \|\hat{F}_m - F\|_n^2 | \mathbf{Z}, \mathbf{C} \right] = \|F_m - F\|_n^2 + \mathbb{E} \left[ \|\hat{F}_m - F_m\|_n^2 | \mathbf{Z}, \mathbf{C} \right]$$

- Bias estimated by  $\gamma_n(\hat{F}_m)$ .
- Variance : as  $\Delta_i$  has Bernoulli distribution

$$\mathbb{E} \left[ \|\hat{F}_m - F_m\|_n^2 | \mathbf{Z}, \mathbf{C} \right] \leq \frac{1}{4} \frac{D_m}{n} \quad \text{with} \quad D_m = D_{m_1}^{(1)} D_{m_2}^{(2)}$$

- **Model selection** : let

$$\hat{m} = \arg \min_{m \in I_n} \left\{ \gamma_n(\hat{F}_m) + \text{pen}(m) \right\} \quad \text{with} \quad \text{pen}(m) = \frac{\theta}{4} \frac{D_m}{n}, \theta > 1$$

# Oracle inequality for the empirical risk

## Theorem

Assume that for every  $b > 0$ , for  $j = 1, 2$ , there exists  $B_j(b)$  s.t.

$$\sum_{m \in I_n^{(j)}} \exp\left(-b\sqrt{D_{m_j}^{(j)}}\right) \leq B_j \quad (\mathbf{H}_0)$$

Then, there exists constants  $C_1$  and  $C_2$  such that,

$$\mathbb{E} \left[ \|\hat{F}_{\hat{m}} - F\|_n^2 \mid \mathbf{C}, \mathbf{Z} \right] \leq C_1 \inf_{m \in I_n} \left\{ \inf_{h \in S_m} \|F - h\|_n^2 + \frac{D_m}{n} \right\} + \frac{C_2}{n}$$

- The model selection estimator realises the bias-variance compromise
- There is no assumptions on the distributions of  $C$  and  $Z$ .
- The result holds for non-random  $\mathbf{Z}$  and/or  $\mathbf{C}$ .

# Integrated risk : additional assumptions

**(H<sub>1</sub>)**  $(C, Z)$  has a density and there exists  $0 < h_0 \leq h_1 < \infty$  s.t.

$$h_0 \leq f_{(C,Z)}(t, z) \leq h_1, \quad \forall (t, z) \in A$$

$\hookrightarrow$  guarantees sufficiently dense observations on the estimation set  $A$  and the equivalence between norms  $\|\cdot\|$  and  $\|\cdot\|_{f_{(C,Z)}} = \mathbb{E}[\|\cdot\|_n^2]$

**(H<sub>2</sub>)** Restriction of the number of models in the collection  $\mathcal{M}_n$  and

$$\max_{m \in \mathcal{M}_n} D_m = \max_{m_1 \in \mathcal{M}_n^{(1)}, m_2 \in \mathcal{M}_n^{(2)}} D_{m_1}^{(1)} D_{m_2}^{(2)} \leq \sqrt{n} / \log(n)$$

**(H<sub>3</sub>)** Assumptions related to the nature of the models.

$\hookrightarrow$  satisfied for classic collections (piecewise polynomials, wavelet, trigonometric basis...)

## Corollary

Assume that  $(\mathbf{H}_0)$ ,  $(\mathbf{H}_1)$ ,  $(\mathbf{H}_2)$  and  $(\mathbf{H}_3)$  hold, there exists constants  $C'_1$  and  $C'_2$  such that,

$$\mathbb{E} \left[ \|\hat{F}_{\hat{m}} - F\|^2 \right] \leq C'_1 \inf_{m \in I_n} \left\{ \inf_{h \in S_m} \|F - h\|^2 + \frac{D_m}{n} \right\} + \frac{C'_2}{n}$$

- Optimality over the collection of estimator up to a multiplicative constant.
- Optimality in a more general sense? Minimax bound over classes of regularity



# Rate of convergence over classes of regularity

**Anisotropic Besov balls**  $\mathcal{B}_{2,\infty}^\beta(L)$  with  $\beta = (\beta_1, \beta_2) \in (\mathbb{R}_+^*)^2$  : generalisation of the function  $\mathcal{C}^{(\beta_1, \beta_2)}$  with square integrable derivative.

## Lemma

Assume that the  $S_m^{(j)}$  are generated from either :

- piecewise polynomials
- wavelets
- trigonometric polynomials

Then there exists a constant  $C_0(L)$  s.t. for all  $F \in \mathcal{B}_{2,\infty}^\beta(L)$ ,

$$\inf_{h \in S_m} \|F - h\|^2 \leq C_0 \left( (D_{m_1}^{(1)})^{-\beta_1} + (D_{m_2}^{(2)})^{-\beta_2} \right)$$

## Corollary

Assume that  $F \in \mathcal{B}_{2,\infty}^\beta(L)$  with  $\beta_1, \beta_2 \geq 1$ . The bias-variance trade-off is obtained with  $\bar{m}$  s.t.

$$D_{\bar{m}_1}^{(1)} \propto n^{\beta_2/(\beta_1+\beta_2+2\beta_1\beta_2)} \quad \text{and} \quad D_{\bar{m}_2}^{(2)} \propto n^{\beta_1/(\beta_1+\beta_2+2\beta_1\beta_2)}$$

and the  $L^2$ -risk of the model selection estimator is upper bounded by

$$\mathbb{E} \left[ \|\hat{F}_{\bar{m}} - F\|^2 \right] \leq C n^{-\bar{\beta}/(\bar{\beta}+1)}$$

with  $\bar{\beta} = 2\beta_1\beta_2/(\beta_1 + \beta_2)$  the harmonic mean.

## Comments

- The dimensions of the optimal model depends on the regularity of the function
- The estimator adapts to different regularities w.r.t. to the two variables.
- Assumption ( $\mathbf{H}_2$ ) on the maximum dimension of models imposes a minimum regularity on  $F$ .
- The rate of convergence with respect to the time variable is not  $1/n$  like in right-censoring framework.

# Minimax rate of convergence

## Theorem

Let  $\beta \in (1, +\infty)^2$ , assume that  $(\mathbf{A}_1^{\text{sup}})$  holds, then there exists a constant  $c(\beta, L, h_1)$  s.t.

$$\inf_{\hat{F}_n} \sup_{F \in \mathcal{B}_{2,\infty}^\beta(L)} \mathbb{E} \left[ n^{\bar{\beta}/(\bar{\beta}+1)} \|\hat{F}_n - F\|^2 \right] \geq c$$

## Comments

- The model selection estimator is minimax over anisotropic Besov balls
- The infimum is taken over all possible estimators : more general result than oracle inequality

# Improvement of the estimator $\widehat{F}_{\widehat{m}}$

- Restriction to  $[0,1]$

$$\tilde{F}_m(x, y) = \begin{cases} 0 & \text{if } \widehat{F}_m(x, y) < 0 \\ \widehat{F}_m(x, y) & \text{if } 0 \leq \widehat{F}_m(x, y) \leq 1 \\ 1 & \text{if } \widehat{F}_m(x, y) > 1 \end{cases}$$

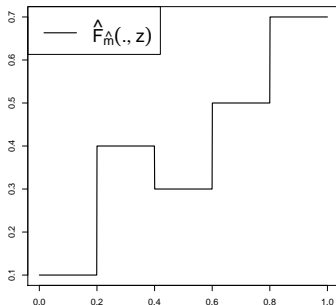
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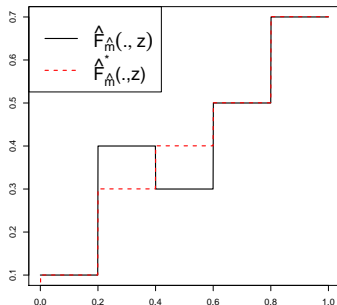


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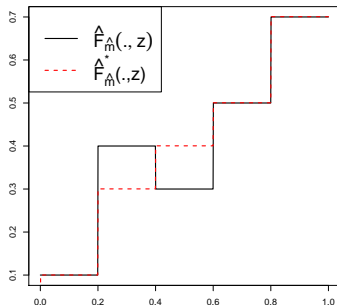


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↪ Decreases the risk of the estimator.

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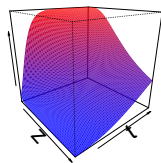


# Simulations

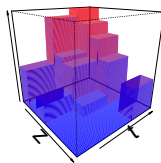
Distribution of the simulated data  $(Z_i, T_i, C_i)_{i=1, \dots, n}$

$$\begin{cases} Z \sim \Gamma(k = 1.5, \theta = 2) \\ T = Z + \varepsilon \quad \text{with} \quad \varepsilon \sim \Gamma(k = 3, \theta = 2) \\ C = Z + \varepsilon' \quad \text{with} \quad \varepsilon' \sim \Gamma(k = 3, \theta = 2) \end{cases}$$

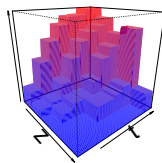
**Model selection estimator of  $F$  with histogram models**



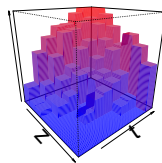
True  $F$



$n=500$

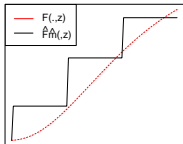


$n=2000$

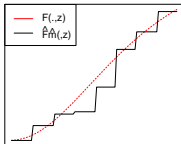


$n=5000$

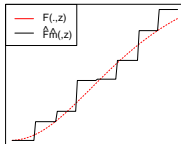
fixed value of  $z = 5$



$t$

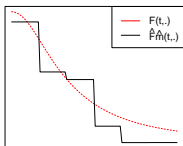


$t$



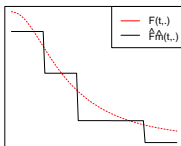
$t$

fixed value of  $t = 10$



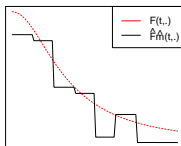
$z$

$n=500$



$z$

$n=2000$



$z$

$n=5000$

- Accurate estimation **require large sample size** due to
  - current status data : low informative
  - bi-dimensional setting without restrictive assumption : dimension curse.

## Simulations (2)

- In right censoring, the **censoring rate**, defined as the proportion of unobserved times of event, impacts the quality of estimation.  
↔ Mean of the censoring rate depends on distribution of  $C$  and  $T$ .

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**Heuristic** : for a given sample size  $n$  and  $Z = z$ ,

- ◇  $F$  is more accurately estimated if observations  $(C_i)_i$  are concentrated on area where  $F$  varies the most
- ◇ High variations of  $F \Leftrightarrow$  high density of  $T$
- ◇ Thus, estimation should improve as distance between densities  $f_C$  and  $f_T$  decreases.

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- ◇  $F$  is more accurately estimated if observations  $(C_i)_i$  are concentrated on area where  $F$  varies the most
- ◇ High variations of  $F \Leftrightarrow$  high density of  $T$
- ◇ Thus, estimation should improve as distance between densities  $f_C$  and  $f_T$  decreases.

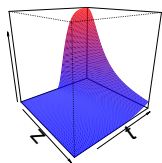
### • Simulations

$$\begin{cases} Z \sim \Gamma(k = 1.5, \theta = 2) \\ T = a + Z \times \varepsilon \quad \text{with} \quad \varepsilon \sim \Gamma(k = 3, \theta = 2) \\ C = Z \times \varepsilon' \quad \text{with} \quad \varepsilon' \sim \Gamma(k = 3, \theta = 2) \end{cases}$$

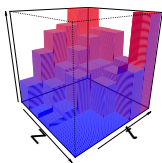
and the parameter  $a$  tunes the distance between  $f_{T|Z}$  and  $f_{C|Z}$ .

$$\text{dist}(a) = \|f_C - f_T\|_{L^1}$$

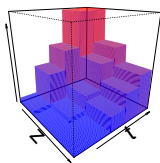
a	0	2	5	10
dist(a)	0	0.63	1.12	1.54



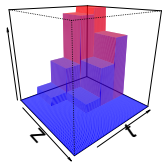
True  $F$



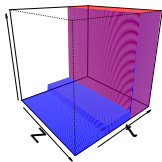
$a = 0$



$a = 2$



$a = 5$



$a = 10$

# Summary

- Framework :
$$\left\{ \begin{array}{l} T_i \text{ unobserved time of interest} \\ C_i \text{ observation time} \\ \Delta_i = \mathbb{1}_{T_i \leq C_i} \text{ current status at time } C_i \\ Z_i \in \mathbb{R} \text{ covariate} \\ C_i \perp T_i | Z_i \end{array} \right.$$
- Least square contrast based on  $\mathbb{E}[\Delta_i | C_i = c, Z_i = z] = F(c, z)$  with  $F$  the conditional c.d.f. of  $T_i$ .
- Model selection estimator
  - ◇ non-parametric estimation in finite dimensional spaces of functions called models.
  - ◇ Data driven-criterion to select a model by estimation of the bias-variance sum
- Oracle inequalities : the selected model realises the bias-variance trade-off
- Minimax optimality
- Require large sample size

# Conclusion and perspectives

- Time and covariate treated the same : unusual  
↔ Minimax optimality validate the method
- Method valid for non-random observation times :  
↔ the distribution of  $C$  is not involved in the estimator (contrary to inverse probability weighted method e.g.)  
↔ for the control empirical risk control, no assumption on the covariate and observation time repartition
- Extension to covariates of dimension  $p$  : require very large sample size  
(limitation to uni-variate model of dimension  $D_{m_j}^{(j)} \leq n^{1/2p}$ )
- Generalisation to probabilistic discriminant classifier.
- Isotonic regression
- Simulations suggest impact of the distance between densities of  $T$  and  $C$ .